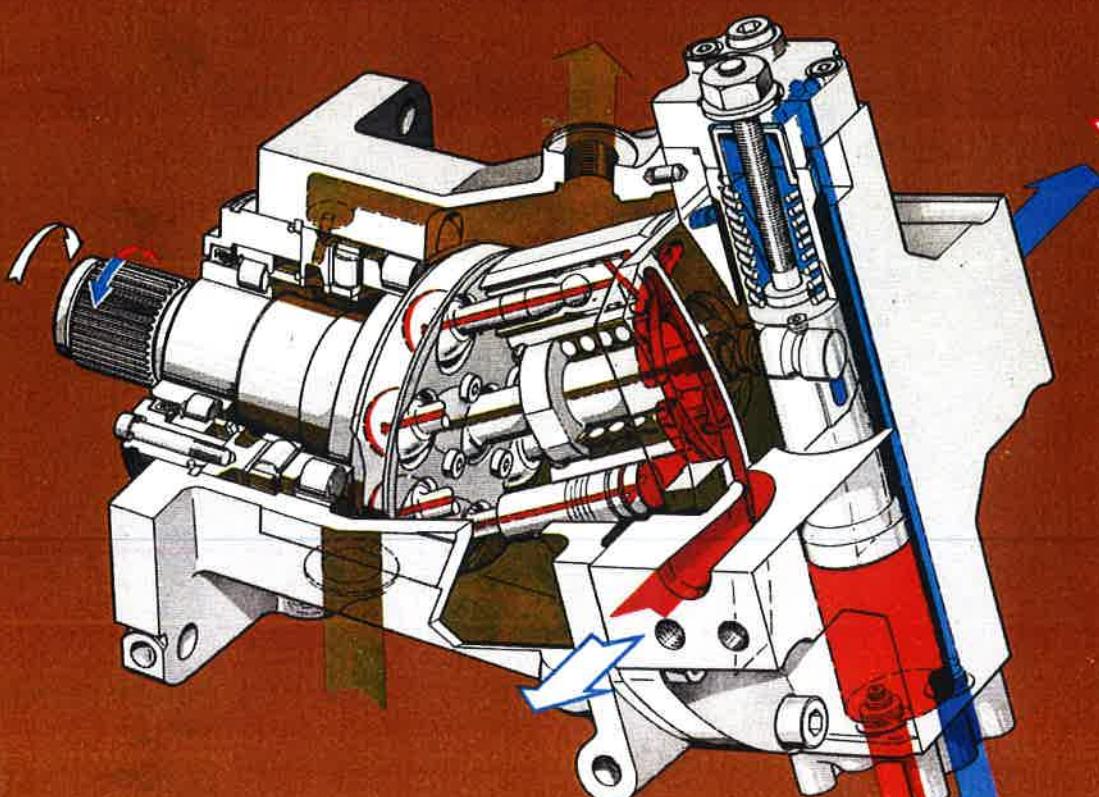
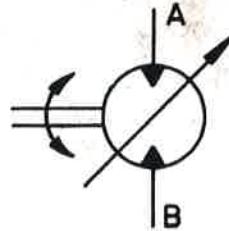


*Linde*

**BMV**

(B = B series)  
(MV = variable motor)

**VARIABLE MOTOR**  
for open and closed  
circuit



## Order code

B	M			TF
Series	Motor	V = pilot pressure controlled (low pressure) R = system pressure regulated (high pressure)	Nominal size (cm <sup>3</sup> /rev) (max. displacement) <b>50,75,105, 140,186,260</b>	Bent axis motor with SAE flange ports

## Basic order information

- minimum displacement
- size

## Additional information for BMR

- regulation starting at .. bar (see controls)

## Description

The BMV/BMR motor displacement can be set to maximum or minimum displacement by changing the head tilt angle.

For equal pressure and input flow the

\* **maximum** displacement provides high output torque at low speed

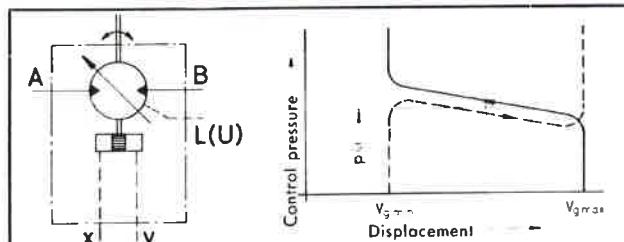
\* **minimum** displacement provides low output torque at high speed.

## Controls

### 1. Two step motor (BMV, flip-flop) \*

Smooth change under load from maximum to minimum displacement and vice-versa.

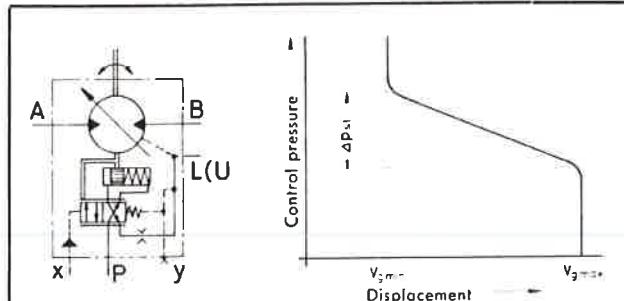
Control pressure  $p_{st} \approx 15$  bar; control by 4/2 valve



### 2. Stepless motor (BMV, remote controlled) \*

Head tilt angle progressively changed between maximum and minimum displacement by means of pilot pressure.

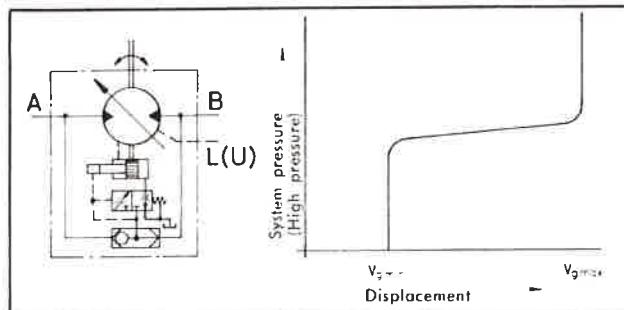
Control pressure range  $\Delta p_{st} = 8$  to 15 bar pilot valve operated



### 3. High pressure regulated motor

Automatic smooth change from minimum to maximum displacement and vice-versa at prescribed system pressure (to be stated when ordering)

Regulation begin range 140 ... 250 bar



\* New: Optionally with or without purge valve!



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### Special technical and design features

- \* extremely compact
- \* mounting dimensions correspond exactly with those of equal displacement fixed motors
- thus: -
- \* optional application of fixed and variable motors and hence easy extension of the output torque and speed range
- thus: -
- \* cost saving due to the possibility of using smaller displacement pumps for the same torque/speed variation

- \* improved efficiency
- furthermore:
- \* very rugged and robust rotating group with output shaft capable of accepting side loads
- \* particularly quiet operation
- \* maximum tilt angle 28 degrees
- \* minimum tilt angle 8 degrees

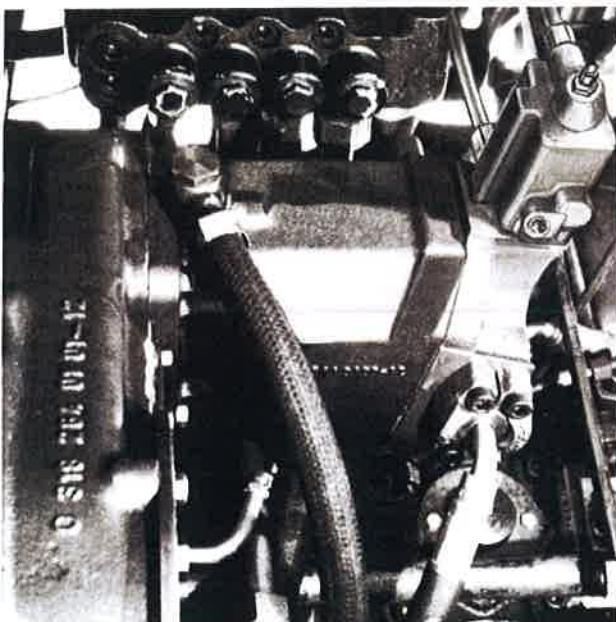


Fig. 1. Single wheel drive of a fork lift truck

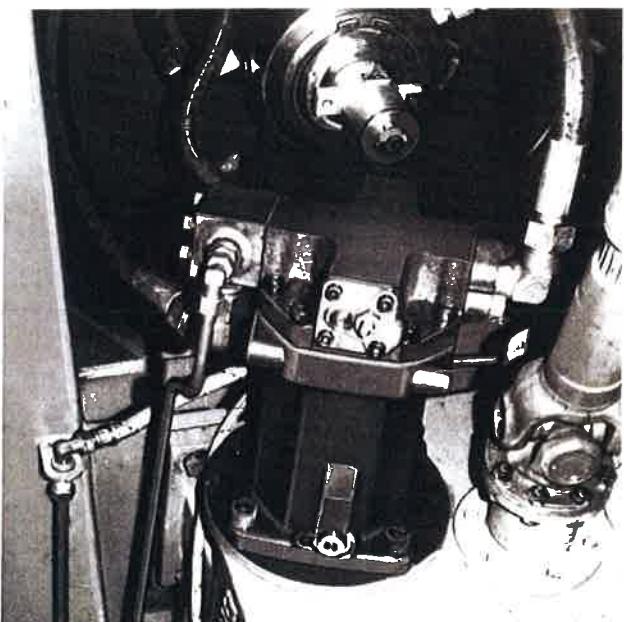


Fig. 2. Differential axle drive of a wheeled excavator

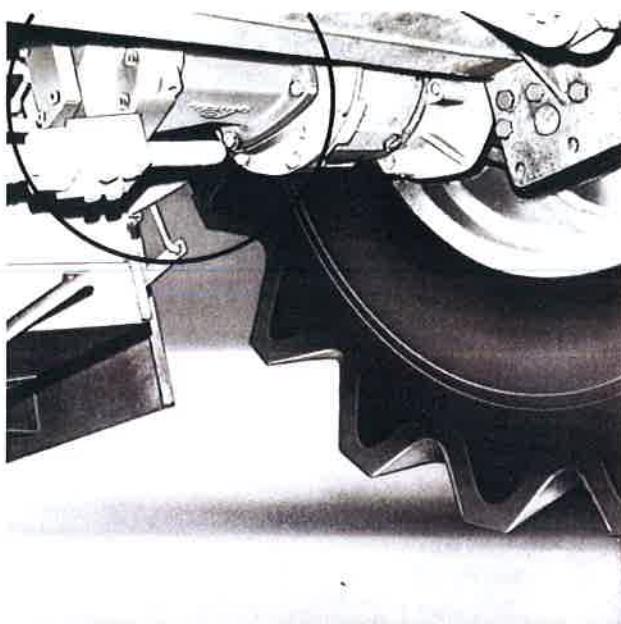


Fig. 3. Single wheel drive of a combine harvester



Fig. 4. Drive to both wheels of a fork lift truck



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## Technical data

Pressures in bar					
Rated size	50	186	260		
Peak pressure*	500	400			
Max. working pressure	420	350			
Continuous pressure (100% working cycle)**	250	200			
Casing pressure (permissible back pressure)	1,5	1,5			

Nominal Size	50	75	105	140	186	260
Displacement in cm <sup>3</sup> /rev						
at max. tilt angle (28°)	50,2	74,9	104,9	139,5	186,2	260,3
at min. tilt angle (8°)	15	22	31	41	55	77

Max. output speed in rev/min (100% working cycle)						
at max. tilt angle (28°)	4200	3700	3300	3000	2800	2500
at min. tilt angle (8°)	5200	4600	4100	3700	3400	3000

Peak output speed in rev/min (intermittent)						
at max. tilt angle (28°)	4500	4000	3600	3300	3000	2700
at min. tilt angle (8°)	6000	5400	4800	4300	3800	3400

The peak output speeds quoted are well within the over-speed reserves of Linde motors. However for noise and efficiency reasons these peak speeds should only be used occasionally e. g. when braking and in bends.

Rotation	
Clockwise and anti-clockwise	

Response Time	
over full stroke – typical (at cont. pressure and max. speed)	1 s
other response times feasible	

## Miscellaneous

### Pressure fluid

Temperature range	-20° ... +90° C
Viscosity range	10 ... 80 cSt
Optimum viscosity	15 ... 25 cSt
Starting viscosity	1000 cSt
Pressure fluid	Mineral oils HL or HLP acc DIN 51 524

### recommended at

working temperature for approx	viscosity class (mm <sup>2</sup> /s = cSt) HL or HLP
30 ... 40° C	22 mm <sup>2</sup> /s bei 40° C
60 ... 70° C	68 mm <sup>2</sup> /s bei 40° C
80 ... 90° C	100 mm <sup>2</sup> /s bei 40° C

Beside the minimum requirements as per DIN 51 524 a qualified hydraulic fluid must also comply with all requirements of a high pressure hydraulic plant. This applies especially to so-called H LPD (detergent) fluids.

Linde recommends to use only such oils whose suitability for high pressure hydraulic installations is confirmed by their producer.

## Filtration

Filtration of the hydraulic circuit is mandatory

Recommended filtration 10 µm  
(filtration rates of 25 ... 40 µm are also acceptable)

Linde recommend 10 µm:

- since 10 µm filters are readily available without additional cost
- since unit life will definitely be increased with finer filtration (less wear)

## Calculations to determine required motor size

Torque	Speed	Reduced tilt angle
$M_d = \frac{\Delta p \cdot V_g \cdot \eta_{red}}{20 \cdot \pi}$	$n = \frac{Q_{eff} \cdot 1000 \cdot \eta_{rot}}{V_g}$	$\sin \alpha_{red} = \frac{V_g \cdot \sin \alpha}{V_g \cdot \max}$
$M_d$ (Nm)	= Shaft output torque	$Q_{eff}$ (l/min) = effective flow
$\Delta p$ (bar)	= in-out pressure differential	$n$ (rev/min) = outputspeed
$V_g$ (cm <sup>3</sup> /rev)	= geometric displacement	$\alpha_{\max}$ (°) = 28 (max. tilt angle)
$V_g \cdot red$ (cm <sup>3</sup> /rev)	= geometric displacement at reduced tilt angle ( $\alpha_{red}$ )	$\eta_{red}$ (%) ≈ 98 (mean mech. efficiency)
$V_g \cdot \max$ (cm <sup>3</sup> /rev)	= geometric displacement at maximum tilt angle ( $\alpha_{\max}$ )	$\eta_{rot}$ (%) ≈ 97 (mean vol. efficiency)

\* Transient pressure over the working pressure, when the motor is still in function.

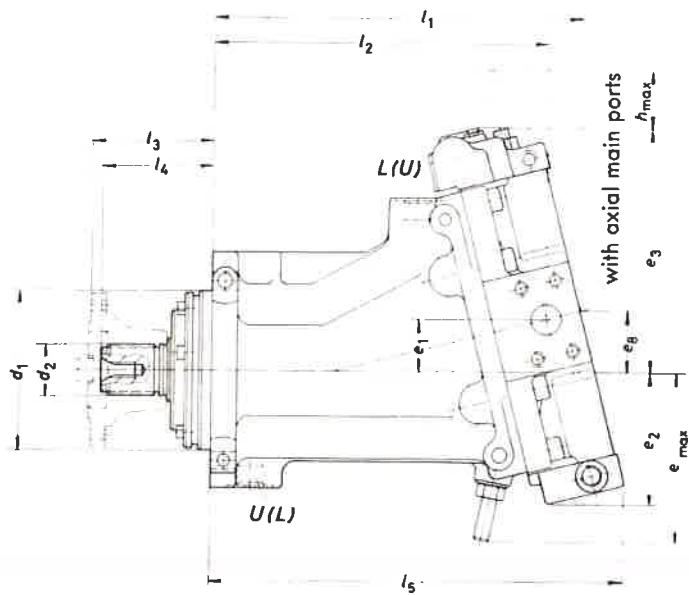
\*\* Continuous pressure to which all the parts of the motor are able to resist.

## Dimensions

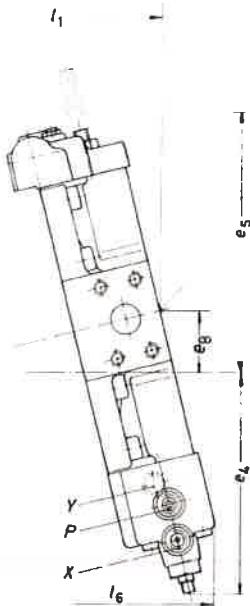
### Motor drawing, dimensions in mm

A and B = Main ports  
 L = Drainport  
 P = Internal control port  
 X and Y = Remote control ports  
 U = Flushing port

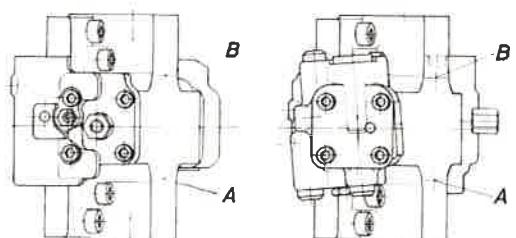
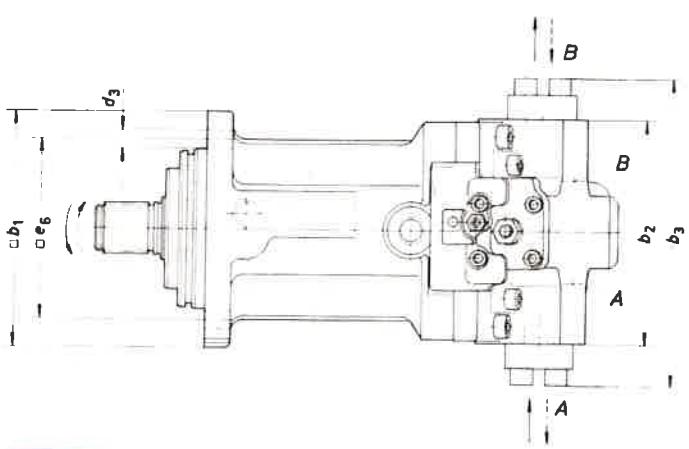
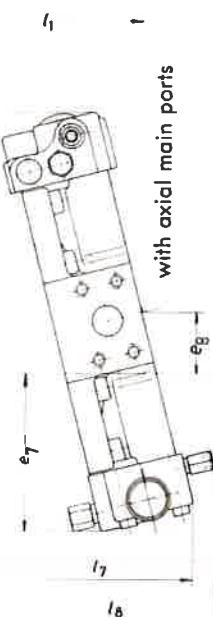
Two step motor



Stepless variable motor



High pressure regulated motor



Rated size (NG)	$\square b_1$	$b_2$	$b_3$	$d_1$	DIN 5482 e9	$d_2$	DIN 5480	$d_3$	$e_{\max}$	$e_1$	$e_2$	$e_3$ (maximal)	$e_4$	$e_5$ (maximal)	$\square e_6$
50	150	147	—	100	B 30 x 27	—	—	12	—	33	93	165	160	—	113,2
75	172	172	237	115	B 35 x 31	—	—	14	129	38,7	107	220	170	201	127,2
105	184	175	237	125	B 40 x 36	—	—	18	123	41,6	108	227	172	208	141,4
140	196	196	262	140	B 45 x 41	—	—	18	139	46	124	252	189	268	141,4
186	210	196	—	160	B 50 x 45	—	—	18	135	49	126	258	185	258	158,4
260	210	246	—	165	—	W 50x2x9g	—	22	142	51,4	—	237	184	258	162

Rated size (NG)	$e_7$	$e_8$	$h_{\max}$	$l_1$	$l_2$	$l_3$	$l_4$	$l_5$	$l_6$	$l_7$	$l_8$	A and B SAE-Flange Size	P, X and Y Pressure	L and U	Weight (maximal) in kg	
50	—	43	23	245	203	81,5	74	255	265	—	—	3/4"	6000 psi	M 14 x 1,5	M 22 x 1,5	24
75	125	53	28	272	242	87,5	77,5	305	315	311	—	1 "	—	M 14 x 1,5	M 22 x 1,5	37
105	124	56,5	31	291,5	261,5	95,5	86,5	324	335	331	—	1 "	—	M 14 x 1,5	M 22 x 1,5	47
140	153	56	—	332	290	115	104	373	382	378	—	1 1/4"	—	M 14 x 1,5	M 22 x 1,5	68
186	151	59,5	—	346	304	131	120	386	395	396	—	1 1/4"	—	M 14 x 1,5	M 22 x 1,5	71
260	151	62,5	—	419,5	375	76,5	76	—	460	460	473	1 1/4"	—	M 14 x 1,5	M 26 x 1,5	79

**Linde**

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in practical applications!**



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